

# NAG Toolbox for MATLAB

## f11me

### 1 Purpose

f11me computes the  $LU$  factorization of a real sparse matrix in compressed column (Harwell–Boeing), column-permuted format.

### 2 Syntax

```
[iprm, nzlump, il, lval, iu, uval, nnzl, nnzu, flop, ifail] = f11me(n,
irowix, a, iprm, thresh, nzlump, nzlump, nzump)
```

### 3 Description

Given a real sparse matrix  $A$ , f11me computes an  $LU$  factorization of  $A$  with partial pivoting,  $P_r A P_c = LU$ , where  $P_r$  is a row permutation matrix (computed by f11me),  $P_c$  is a (supplied) column permutation matrix,  $L$  is unit lower triangular and  $U$  is upper triangular. The column permutation matrix,  $P_c$ , must be computed by a prior call to f11md. The matrix  $A$  must be presented in the column permuted, compressed column (Harwell–Boeing) format.

The  $LU$  factorization is output in the form of four one-dimensional arrays: integer arrays **il** and **iu** and real-valued arrays **lval** and **uval**. These describe the sparsity pattern and numerical values in the  $L$  and  $U$  matrices. The minimum required dimensions of these arrays cannot be given as a simple function of the size parameters (order and number of nonzero values) of the matrix  $A$ . This is due to unpredictable fill-in created by partial pivoting. f11me will, on return, indicate which dimensions of these arrays were not adequate for the computation or (in the case of one of them) give a firm bound. You should then allocate more storage and try again.

### 4 References

Demmel J W, Eisenstat S C, Gilbert J R, Li X S and Li J W H 1999 A Supernodal Approach to Sparse Partial Pivoting *SIAM J. Matrix Anal. Appl.* **20** 720–755

Demmel J W, Gilbert J R and Li X S 1999 An Asynchronous Parallel Supernodal Algorithm for Sparse Gaussian Elimination *SIAM J. Matrix Anal. Appl.* **20** 915–952

### 5 Parameters

#### 5.1 Compulsory Input Parameters

1: **n** – **int32 scalar**

$n$ , the order of the matrix  $A$ .

*Constraint:*  $n \geq 0$ .

2: **irowix(\*)** – **int32 array**

**Note:** the dimension of the array **irowix** must be at least  $nnz$ , the number of nonzeros of the sparse matrix  $A$ .

The row index array of sparse matrix  $A$ .

3: **a(\*)** – **double array**

**Note:** the dimension of the array **a** must be at least  $nnz$ , the number of nonzeros of the sparse matrix  $A$ .

The array of nonzero values in the sparse matrix  $A$ .

4: **iprm**(7 × n) – int32 array

Contains the column permutation which defines the permutation  $P_c$  and associated data structures as computed by function f11md.

5: **thresh** – double scalar

The diagonal pivoting threshold,  $t$ . At step  $j$  of the Gaussian elimination, if  $|A_{jj}| \geq t \left( \max_{i \geq j} |A_{ij}| \right)$ , use  $A_{jj}$  as a pivot, otherwise use  $\max_{i \geq j} |A_{ij}|$ . A value of  $t = 1$  corresponds to partial pivoting, a value of  $t = 0$  corresponds to always choosing the pivot on the diagonal (unless it is zero).

*Constraint:*  $0 \leq \text{thresh} \leq 1$ .

*Suggested value:* **thresh** = 1.0. Smaller values may result in a faster factorization, but the benefits are likely to be small in most cases. It might be possible to use **thresh** = 0.0 if you are confident about the stability of the factorization, for example, if  $A$  is diagonally dominant.

6: **nzlmx** – int32 scalar

Indicates the available size of array **il**. The dimension of **il** should be at least  $7 \times n + \text{nzlmx} + 4$ . A good range for **nzlmx** that works for many problems is  $nnz$  to  $8 \times nnz$ , where  $nnz$  is the number of nonzeros in the sparse matrix  $A$ . If, on exit, **ifail** = 2, the given **nzlmx** was too small and you should attempt to provide more storage and call the function again.

*Constraint:*  $\text{nzlmx} \geq 1$ .

7: **nzlumx** – int32 scalar

Indicates the available size of array **lval**. The dimension of **lval** should be at least **nzlumx**.

*Constraint:*  $\text{nzlumx} \geq 1$ .

8: **nzumx** – int32 scalar

Indicates the available sizes of arrays **iu** and **uval**. The dimension of **iu** should be at least  $2 \times n + \text{nzumx} + 1$  and the dimension of **uval** should be at least **nzumx**. A good range for **nzumx** that works for many problems is  $nnz$  to  $8 \times nnz$ , where  $nnz$  is the number of nonzeros in the sparse matrix  $A$ . If, on exit, **ifail** = 3, the given **nzumx** was too small and you should attempt to provide more storage and call the function again.

*Constraint:*  $\text{nzumx} \geq 1$ .

## 5.2 Optional Input Parameters

None.

## 5.3 Input Parameters Omitted from the MATLAB Interface

None.

## 5.4 Output Parameters

1: **iprm**(7 × n) – int32 array

Part of the array is modified to record the row permutation  $P_r$  determined by pivoting.

2: **nzlumx** – int32 scalar

If **ifail** = 4, the given **nzlumx** was too small and is reset to a value that will be sufficient. You should then provide the indicated storage and call the function again.

3: **il**( $7 \times n + \text{nzlmx} + 4$ ) – **int32 array**

Encapsulates the sparsity pattern of matrix  $L$ .

4: **lval**(\*) – **double array**

**Note:** the dimension of the array **lval** must be at least **nzlumx**.

Records the nonzero values of matrix  $L$  and some of the nonzero values of matrix  $U$ .

5: **iu**( $2 \times n + \text{nzumx} + 1$ ) – **int32 array**

Encapsulates the sparsity pattern of matrix  $U$ .

6: **uval**(**nzumx**) – **double array**

Records some of the nonzero values of matrix  $U$ .

7: **nnzl** – **int32 scalar**

The number of nonzero values in the matrix  $L$ .

8: **nnzu** – **int32 scalar**

The number of nonzero values in the matrix  $U$ .

9: **flop** – **double scalar**

The number of floating-point operations performed.

10: **ifail** – **int32 scalar**

0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**ifail** = 1

On entry, **n** < 0,  
or **nzlmx** < 1,  
or **nzlumx** < 1,  
or **nzumx** < 1,  
or **thresh** < 0.0,  
or **thresh** > 1.0.

**ifail** = 2

**nzlmx** was not large enough. You should repeat the call with a larger value of **nzlmx**, providing more storage for the output array **il**.

**ifail** = 3

**nzumx** was not large enough. You should repeat the call with a larger value of **nzumx**, providing more storage for the output arrays **iu** and **uval**.

**ifail** = 4

**nzlumx** was not large enough. You should repeat the call with the value of **nzlumx** returned on exit, providing more storage for the output array **lval**.



```

        int32(2);
        int32(0);
        int32(8);
        int32(6);
        int32(4);
        int32(4);
        int32(2);
        int32(11);
        int32(8);
        int32(6);
        int32(1);
        int32(2);
        int32(3);
        int32(4);
        int32(5);
        int32(2);
        int32(2);
        int32(2);
        int32(2);
        int32(1);
        int32(1);
        int32(1);
        int32(1);
        int32(2);
        int32(0)];
    thresh = 1;
    nzlmx = int32(88);
    nzlumx = int32(88);
    nzumx = int32(88);
    [iprmOut, nzlumxOut, il, lval, iu, uval, nnzl, nnzu, flop, ifail] = ...
        f11me(n, irowix, a, iprm, thresh, nzlmx, nzlumx, nzumx)

```

```

iprmOut =
    1
    0
    4
    3
    2
    4
    3
    1
    2
    0
    2
    0
    8
    6
    4
    4
    2
    11
    8
    6
    1
    2
    3
    4
    5
    2
    2
    2
    2
    1
    1
    1
    1
    2
    0
    0
    88

```

```
il =  
    array elided  
lval =  
    array elided  
iu =  
    array elided  
uval =  
    array elided  
nnzl =  
        9  
nnzu =  
        10  
flop =  
        19  
ifail =  
        0
```

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